

This Page Is Inserted by IFW Operations
and is not a part of the Official Record

BEST AVAILABLE IMAGES

Defective images within this document are accurate representations of the original documents submitted by the applicant.

Defects in the images may include (but are not limited to):

- BLACK BORDERS
- TEXT CUT OFF AT TOP, BOTTOM OR SIDES
- FADED TEXT
- ILLEGIBLE TEXT
- SKEWED/SLANTED IMAGES
- COLORED PHOTOS
- BLACK OR VERY BLACK AND WHITE DARK PHOTOS
- GRAY SCALE DOCUMENTS

IMAGES ARE BEST AVAILABLE COPY.

**As rescanning documents *will not* correct images,
please do not report the images to the
Image Problem Mailbox.**

THIS PAGE BLANK (USPTO)

PCT

WORLD INTELLECTUAL PROPERTY ORGANIZATION
International Bureau



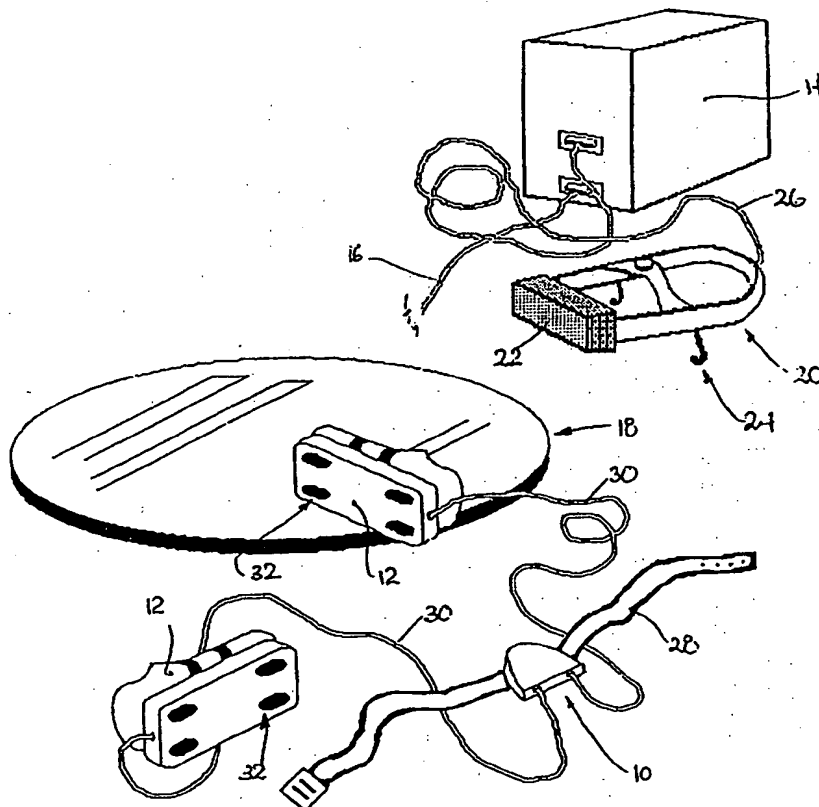
INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(51) International Patent Classification ⁶: G09B 9/00	A1	(11) International Publication Number: WO 96/36955 (43) International Publication Date: 21 November 1996 (21.11.96)
(21) International Application Number: PCT/AU96/00298 (22) International Filing Date: 16 May 1996 (16.05.96) (30) Priority Data: PN 2989 16 May 1995 (16.05.95) AU (71)(72) Applicant and Inventor: PHILLIPS, Scott, Andrew [AU/AU]; 2A Hampden Road, Battery Point, TAS 7004 (AU). (74) Agent: GRIFFITH HACK & CO.; G.P.O. Box 4164, Sydney, NSW 2001 (AU).		(81) Designated States: AL, AM, AT, AU, AZ, BB, BG, BR, BY, CA, CH, CN, CZ, DE, DK, EE, ES, FI, GB, GE, HU, IS, JP, KE, KG, KP, KR, KZ, LK, LR, LS, LT, LU, LV, MD, MG, MK, MN, MW, MX, NO, NZ, PL, PT, RO, RU, SD, SE, SG, SI, SK, TJ, TM, TR, TT, UA, UG, US, UZ, VN, ARIPO patent (KE, LS, MW, SD, SZ, UG), Eurasian patent (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European patent (AT, BE, CH, DE, DK, ES, FI, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE), OAPI patent (BF, BJ, CF, CG, CI, CM, GA, GN, ML, MR, NE, SN, TD, TG). Published <i>With international search report.</i>

(54) Title: A POSITIONING DEVICE

(57) Abstract

A positioning device for maintaining a user at a datum includes a positional sensor (10) adapted for sensing the user's movement away from the datum; motive means (12) that is operable on the user to return the user to the datum; and a controller (14) adapted to receive a signal from the positional sensor (10) and, pursuant to the user's deviation from the datum, to activate the motive means (12) so that it operates on the user to return the user to the datum.



FOR THE PURPOSES OF INFORMATION ONLY

Codes used to identify States party to the PCT on the front pages of pamphlets publishing international applications under the PCT.

AM	Armenia	GB	United Kingdom	MW	Malawi
AT	Austria	GE	Georgia	MX	Mexico
AU	Australia	GN	Guinea	NE	Niger
BB	Barbados	GR	Greece	NL	Netherlands
BE	Belgium	HU	Hungary	NO	Norway
BF	Burkina Faso	IE	Ireland	NZ	New Zealand
BG	Bulgaria	IT	Italy	PL	Poland
BJ	Benin	JP	Japan	PT	Portugal
BR	Brazil	KE	Kenya	RO	Romania
BY	Belarus	KG	Kyrgyzstan	RU	Russian Federation
CA	Canada	KP	Democratic People's Republic of Korea	SD	Sudan
CF	Central African Republic	KR	Republic of Korea	SE	Sweden
CG	Congo	KZ	Kazakhstan	SG	Singapore
CH	Switzerland	LI	Liechtenstein	SI	Slovenia
CI	Côte d'Ivoire	LK	Sri Lanka	SK	Slovakia
CM	Cameroon	LR	Liberia	SN	Senegal
CN	China	LT	Lithuania	SZ	Swaziland
CS	Czechoslovakia	LU	Luxembourg	TD	Chad
CZ	Czech Republic	LV	Latvia	TG	Togo
DE	Germany	MC	Monaco	TJ	Tajikistan
DK	Denmark	MD	Republic of Moldova	TT	Trinidad and Tobago
EE	Estonia	MG	Madagascar	UA	Ukraine
ES	Spain	ML	Mali	UG	Uganda
FI	Finland	MN	Mongolia	US	United States of America
FR	France	MR	Mauritania	UZ	Uzbekistan
GA	Gabon			VN	Viet Nam

- 1 -

A POSITIONING DEVICEFIELD OF THE INVENTION

5 The present invention relates to a positioning device, in particular to a device that can be used with virtual reality (VR) simulation apparatus. The device will be described primarily with reference to its use in virtual reality simulations, but it should be appreciated that the applications of the device are not so limited.

BACKGROUND ART

10 Virtual reality simulation involves presenting sensory information to a user of VR simulation apparatus, being any number of simulated scenarios, usually removed from the present environment of the user. In the evolution of VR simulation, users now wear goggles or
15 headsets which include a pair of stereoscopically arranged liquid crystal projector screens, projecting for viewing to the user a computer-generated graphical environment. The headset also includes speakers for presenting accompanying aural sensations. The user often
20 wears gloves, suits, etc fitted with sensors which sense movement of the user's body parts from a predetermined orientation and then, via a central processing unit, simulate (reproduce) that movement in the virtual realm.

User movement such as walking or running, etc,
25 however, has only been simulated in abstract, whereby, the central processing unit projects graphically to user walking, running, etc, but without user walking or running taking place in the user's actual environment. Thus, the illusion of walking, running etc is lost to the
30 user, because it does not correspond with their present circumstances and hence the simulation is somewhat reduced or detracted from.

Attempts have been made with VR apparatus to simulate walking, running etc, but the apparatus must

SUBSTITUTE SHEET (RULE 26)

- 2 -

then be housed in large areas or must itself be quite large. To date, this has proved to be economically unfeasible and difficult to implement.

SUMMARY OF THE INVENTION

5 The present invention provides a positioning device for maintaining a user at a datum including:

- a positional sensor adapted for sensing the user's movement away from the datum;
- motive means that is operable on the user to
10 return the user to the datum; and
- a controller adapted to receive a signal from the positional sensor and, pursuant to the user's deviation from the datum, to activate the motive means so that it operates on the user to return the user to the
15 datum.

By employing such a device with VR simulation apparatus, apparatus dimensions can be maintained at around existing sizes, and additional capital outlay can be maintained at realistic levels. For example, a user
20 can walk with such a device but can be held within a certain area so that in the virtual realm it appears to the user that they are walking (ie. they receive normal physical sensations of walking, and further this walking is simulated for them in the virtual realm), and yet the
25 user's position is confined to a small area.

Preferably the sensor is adapted for mounting to the user at a position so that the datum is generally centred on a vertical line extending through the sensor; and, when the user has moved from the datum, the motive means
30 is:

- (a) adapted for mounting to the user and so that it returns the user to the datum only when brought into contact with surrounding ground; or
- (b) separate from the user and adapted for
35 acting on the user to return the user to the datum only when the user is in contact therewith.

SUBSTITUTE SHEET (RULE 26)

- 3 -

Thus two modes of embodying the device can be employed, one where the motive means is attached to the user, and one where it is separate from the user, (eg. where the user stands on the motive means and it has a conveying type of effect).

In this regard, the motive means can either be adapted for attachment to a user's feet or it can be positioned at or within a surface, so in either case when the user is walking, the user is continually returned to the datum.

The motive means can be located within a type of shoe attachable to each foot of the user and can include:

- a tracking means arranged for engaging and moving the shoe relative to the ground upon which the user walks in use; and

- a motor means operable on the tracking means to drive the same, wherein the motor means is responsive to the signal from the controller whereby, upon activation, it drives the tracking means so that each user's shoe is moved on the ground to return the user to the datum.

In this regard, the tracking means can be a plurality of track balls, each rotatably retained within a respective socket formed in the underside of the shoe but so as to partially protrude therefrom to engage the ground, and the motor means is a plurality of motors housed within the shoe, each connected to one or more drive shafts which in turn are operable on the track balls to cause rotation thereof, and such that when each shoe is brought into contact with the ground, the driven rotation of the track balls causes the shoe to be moved so that the user is returned to the datum.

It is also preferred that each shoe incorporates an additional positional sensor so that the controller can sense any deviation that each foot has from a forward facing orientation when standing and a forwardly directed walking orientation when walking, and so that the motive means is activated accordingly by the controller to return the user to the datum.

Alternatively, when the device is separate from the user, the motive means can include a plurality of track balls arranged within a floor, such that when standing thereon, the user's feet or shoes engage a certain number of track balls, and wherein when the user is walking on the floor the track balls are driven by a motor means that is responsive to the signal from the controller, whereby upon activation, the motor means drives a predetermined number of the track balls so that the user's feet (or shoes) are moved to return the user to the datum.

The datum can be an area (eg. a circular area in which the user is to be maintained) or for computational purposes, can be an imaginary vertical axis to which the motive means returns the user (eg. so that the sensor becomes aligned with that vertical axis).

BRIEF DESCRIPTION OF THE DRAWINGS

Notwithstanding any other forms which may fall within the scope of the present invention, preferred forms of the invention will now be described, by way of example only, with reference to the accompanying drawings in which:

Figure 1 shows a perspective view of one type of preferred positioning device according to the invention;

Figure 2 shows a perspective exploded underside view of part of the device shown in Figure 1;

Figure 3 shows a perspective detail of part of the device shown in Figure 2;

Figure 4 shows a component in perspective view, being a part of the device shown in Figure 2; and

Figure 5 shows a perspective view of an alternative positional device according to the invention.

MODES FOR CARRYING OUT THE INVENTION

Referring to Figure 1, a positioning device for

- 5 -

maintaining a user at a datum can include a positional sensor in the form of tracker 10 for sensing the user's movement away from the datum, a motive means in the form of motorised shoes 12 which, when worn by a user, can be operated to move the user back to the datum, and a controller in the form of computer (or IC controller) 14 which can be programmed so that it is responsive to a signal from the tracker 10 and so that it causes the motorised shoes to operate in a manner that returns the user to the datum (eg. when the user is walking).

The computer 14 either communicates remotely with tracker 10 (eg. via radiowave, infrared signals etc) or is connected to the tracker via communication line 16. In this regard, the tracker may be a Space Pad™ tracker (trade mark of Ascension Technology Corporation). Trackers like the Space Pad™ tracker drive a transmitter which can be a long strand (loop) of electrically conductive wire arranged in matting 18 upon which the user stands. The datum to which the user is returned is preferably also defined by (or is within) the boundaries of the matting. Thus, in one preferred mode of use, the user stands on and is confined to the matting when walking, running etc.

When the device is used with virtual reality simulation apparatus, including virtual reality simulation software loaded into computer 14, the user may also employ a headset 20, which incorporates a projector housing 22 having fitted therein a pair of stereoscopically adjusted liquid crystal screens, one for each eye, (as is known). The headset also includes earpiece speakers 24 which fit into the user's ears. Thus, the headset provides both visual and aural imagery to the user as part of the virtual reality simulation. The graphical and aural information and power for the headset is supplied via second communication line 26.

The user can fit the tracker to his/her torso by strapping a belt 28 therearound. Typically, the tracker is located adjacent to the user's navel (although it may

SUBSTITUTE SHEET (RULE 26)

- 6 -

also be located at the user's forehead), the navel being close to the user's centre of gravity. Thus, the tracker is positioned to be most sensitive to user movement such as walking (ie. when commencing walking, movement simultaneously with leg movement commences at the user's centre of gravity).

Each motorised shoe may also include a positional tracker (not shown) which can sense deviations of the shoe from predetermined inclinations (described below). This information is fed to the tracker 10 via lines 30 and is then on-fed to the computer.

Each motorised shoe includes four socket-recesses 32 located in the underside thereof, each housing a drive ball mechanism (described in more detail below) and which is configured when activated to drive the shoe in any direction in the horizontal plane.

In one mode of use, the user attaches the tracker around their waist using belt 28, and then places the shoes 12 on each foot and also places headset 20 thereon. (In addition, the user may attach VR-type gloves, bodysuit etc, but not described herein). The user then stands centrally on matting 18, usually in a balanced position with both feet slightly apart. The computer is then configured so that this position is recorded as the start (or datum) position and then the virtual reality simulation can commence.

As the user starts walking, tracker 10 moves forward. This movement is reproduced by the computer (which receives positional information from tracker 10 and from the shoe trackers) in the virtual realm so that it appears to the user that they are walking in the graphically presented simulation. The movement also activates the motorised shoes so that upon placement of each shoe on the matting, the user's foot is returned (moved back in an opposite sense) so that the user is generally maintained at the datum. If the user is pigeon-toed or skew-footed, the sensors in the shoes record this so that the shoe is moved back to the datum

SUBSTITUTE SHEET (RULE 26)

- 7 -

position accordingly, and similarly for any turning that the user may engage in when walking, or for any deviation from a directly forward walking or backward walking stride.

5 Thus, the user has the sensation of walking, but a large scale apparatus is not needed to accommodate the walking. Rather, the user can be maintained at (or around) the datum.

10 Referring now to Figures 2 to 4, a more detailed description of the construction and operation of the motorised shoes 12 will be given. Figure 2 shows a perspective view of the motorised shoe 12, with the shoe upper portion removed therefrom for clarity.

15 A lift plate 34 is positioned above the drive mechanism and is pivotable with respect to the mechanism. For example, the plate 34 can be raised and lowered hydraulically, pneumatically or via a motor drive when a user is walking with the shoe, to simulate the heel lift and heel return that occurs through a user's stride. In
20 this manner, the shoe drive mechanism can be maintained basically parallel to the ground so that the drive balls (described below) are brought evenly into contact therewith (eg. all balls simultaneously engaging the ground) when the shoe is replanted on the ground. This
25 action assists in the device allowing the user to engage in walking that is as close as possible to a natural walking style. The sequence of plate lift and lowering can be programmed or sensed and controlled by the computer for each individual user (eg. where the computer
30 learns or memorises each user's walking peculiarities and records these for the subsequent times when that user returns to use the device).

35 A power source 36 (eg. battery, or electrical transformer) is located in the centre of a mechanism casing 38. The power source drives a number of motors 40 housed within the casing in a variety of sequences as determined by controlling software in computer 14.

Typically the motors are low inertia, high torque

- 8 -

type motors to enable rapid starting and arrest, and to readily accommodate users of varying weights.

5 The casing 38 has the socket recesses 32 formed in the underside thereof which house four drive balls, namely, front drive balls 42, 42' and rear drive balls 44, 44' and such that a portion of each ball (eg. 2mm) protrudes beyond the underside of the casing for engaging the ground. The drive balls are drivingly rotated by the mechanism so that when they are brought into contact with the ground, they cause the motorised shoe to be moved over the ground (ie. when fitted to the user).

10 Driving of the drive balls is accomplished by a plurality of drive rods. Front transverse drive rod pair 46 and rear transverse drive rod pair 48 cause, respectively, the front drive balls 42, 42' and the rear drive balls 44, 44' to be driven either longitudinally forwardly in the direction of arrow LF or longitudinally rearwardly in the direction of arrow LR, depending on the way in which the rods are rotated. On the other hand, 20 left longitudinal drive rod pair 50 and right longitudinal drive rod pair 52 cause, respectively, left drive balls 42, 44 and right drive balls 42', 44' to move the shoe transversely (either transversely to the left in the direction of arrow TL or transversely to the right in the direction of arrow TR).

25 Each rod has an end gear 56 arranged thereon to define a pair of end gears at each end of each rod pair. These gears are connected together at each end by a respective intermediate gear 58 so that driving rotation of one of the rods is translated to the other rod and thus for forward or transverse movement, each drive ball is driven by two drive rods. The gears can be engaged by a respective motor at each end to drive the drive rods. For example, a motor can be connected directly (or via 35 gearing etc) to the intermediate gear, which when rotated, rotates both end gears 56 and hence both respective drive rods to then drive one or two of the drive balls.

SUBSTITUTE SHEET (RULE 26)

- 9 -

Alternatively, each drive rod pair is driven by rotating contact from a pair of motor driven rollers 54 (only two such motor driven rollers are shown in the drawings for clarity). In Figure 2, the motor driven rollers 54 engage and rotate the left rod of the front transverse drive rod pair 46 and rotate it either clockwise or counter-clockwise based on information from the computer.

As seen in Figure 3, drive ball 42 is driven by front transverse drive rod pair 46 and left longitudinal drive rod pair 50. Because the transverse drive rod pair overlays the longitudinal drive rod pair, each transverse drive rod is provided with an extension roller 60 to enable drive contact with the drive ball (ie. so that the transverse drive rod rotation can be imparted to the drive ball). The criss-crossing of the transverse and longitudinal drive rod pairs at each drive ball also provides a supporting base to each socket, whereby the weight of the user and the shoe is transferred via the drive rods to each drive ball.

To achieve only longitudinal forward or rearward motion, only the front and/or rear transverse drive rod pairs are rotated by the motors 40. Similarly, to achieve only left or right transverse motion, only the left and/or right longitudinal drive rod pairs are rotated by the motors. To achieve diagonal, curvilinear or other directional movement of the shoes in the horizontal plane, both the transverse and longitudinal drive rod pairs are driven simultaneously and, depending on the direction of motion required, at different rates (speeds).

Figure 4 shows a transverse drive rod clearly illustrating the position of the extension rollers 60.

Referring to Figure 5, where like reference numerals will be used to denote like parts, instead of employing motorised shoes, a platform 62 having a plurality of drive balls 64 arranged therein in a grid-like formation on the upper surface of the platform is provided. The

- 10 -

balls are each arranged in respective sockets and protrude slightly above the upper surface (eg. by 2mm) for ease of engagement by the user. Each row of drive balls in either the longitudinal or transverse direction is driven by drive rods in a similar manner to the mechanism operation of Figure 2. Thus, each individual drive ball sits on and is driven by a pair of transverse and a pair of longitudinal drive rods. A plurality of respective motors is arranged within and is either connected to the drive rods directly via motor driven rollers, or directly engages the end gears or intermediate gears, such motors being located within the platform itself.

In one mode of use, a user again stands on the platform, generally centrally and with the user's feet spaced slightly apart. A datum position is then recorded by the computer software and, once the user is fitted with the VR apparatus, and commences walking, the walking movement of the user is sensed and a predetermined number of drive balls are activated. For example, with the user stepping forward on the platform 62 when facing wall 66, the drive balls in say the top three or four rows are rotated so that after stepping thereon, the user's foot is moved backwardly. Shortly thereafter, the user steps forward with the other foot and, when lifting the other foot, further or move successive central rows are activated to progressively move the user's first foot back towards it's original position. A simultaneous and similar sequence of activation then occurs for the other foot. Activating combinations of transverse and longitudinal rows is employed when the user walks diagonally, turns left or right, walks rearwardly etc, and all the necessary calculations are performed rapidly by the computer 14.

Typically the tracker 10 is a 3-dimensional tracking device, such as a Space Pad™ tracker or a Polhemus™ sensor (trade mark of 3 Space Corp). The platform 18 or the platform 62 can incorporate a magnetic source, a

SUBSTITUTE SHEET (RULE 26)

- 11 -

wiring loop or other similar means to provide an initial reference point (datum) to and within which the user is to be maintained.

5 The or each tracker (ie. including the trackers used in the motorised shoes) can be configured to output six channels of information that correspond to X, Y and Z positions in 3-dimensional space and X, Y and Z orientation relative to the magnetic source, wiring or other sensor in the platform 62 or matting 18.

10 As an alternative to computer 14 controlling the motorised shoes 12 or the platform drive balls 64, an intermediate integrated circuit located in the platform, in the tracker 10 itself then receives the six channel signal from each tracker. This information is used to
15 calculate the user's position (and the computer can then re-display it in the virtual realm). At the same time, the X (ie. transverse) and Z (ie. longitudinal) position signals can be used to calculate the degree of rotation required in the specific drive balls (either in the
20 motorised shoes 12 or platform drive balls 64) to return the user (eg. the sensor) to the datum.

Thus, essentially the user can engage in a normal walking motion, which provides to the user a complete illusion of movement in the horizontal plane, whilst in
25 actual fact the movements are confined within a comparatively small area. However, in the virtual realm it appears to the user that they are in fact moving through horizontal space (as is desirable for maximum simulation in the virtual realm).

30 The use of the device in VR apparatus is not limited to walking, running etc and may be employed where the user is simulating other types of motion, for example, from sitting positions.

Typically, many of the components are formed from
35 light-weight but hard-wearing plastics to provide the user with maximum freedom of movement. However, hard-wearing components subject to high torque and high twisting forces are typically formed from treated steel

alloys (eg. hardened at the outer surface thereof).

Whilst the invention has been described with reference to a number of preferred embodiments, it should be appreciated that the invention can be embodied in many
5 other forms.

- 13 -

CLAIMS:

1. A positioning device for maintaining a user at a datum including:

5 - a positional sensor adapted for sensing the user's movement away from the datum;

 - motive means that is operable on the user to return the user to the datum; and

10 - a controller adapted to receive a signal from the positional sensor and, pursuant to the user's deviation from the datum, to activate the motive means so that it operates on the user to return the user to the datum.

15 2. A device as claimed in claim 1, wherein the sensor is adapted for mounting to the user at a position so that the datum is generally centred on a vertical line extending through the sensor; and, when the user has moved from the datum, the motive means is:

20 (a) adapted for mounting to the user and so that it returns the user to the datum only when brought into contact with surrounding ground; or

 (b) separate from the user and adapted for acting on the user to return the user to the datum only when the user is in contact therewith.

25 3. A device as claimed in claim 2, wherein in (a) the motive means is adapted for attachment to a user's feet so that, when walking, the user is continually returned to the datum.

30 4. A device as claimed in claim 2, wherein in (b) the motive means is positioned at or within a surface on which a user can be supported and so that the user is continually returned to the datum when walking on the surface.

5. A device as claimed in claim 3, wherein the motive means is located within a type of shoe attachable to each

- 14 -

foot of the user and includes:

- a tracking means arranged for engaging and moving the shoe relative to the ground upon which the user walks in use; and

5 - a motor means operable on the tracking means to drive the same, wherein the motor means is responsive to the signal from the controller whereby upon activation, it drives the tracking means so that each user's shoe is moved on the ground to return the user to the datum.

10 6. A device as claimed in claim 5, wherein the tracking means is a plurality of track balls, each rotatably retained within a respective socket formed in the underside of the shoe but so as to partially protrude therefrom, and the motor means is a plurality of motors
15 housed within the shoe, each connected to one or more drive shafts which in turn are operable on the track balls to cause rotation thereof, and such that when each shoe is brought into contact with the ground, the driven rotation of the track balls causes the shoe to be moved
20 so that the user is returned to the datum.

25 7. A device as claimed in claim 6, wherein each shoe includes four track balls, with two located at opposing left and right sides at a front underside and two located at opposing left and right sides at a rear underside of
30 the shoe, and wherein both of the two front track balls and both of the two rear track balls are engaged by a respective pair of transversely extending drive shafts which, when rotated by respective motors impart forward or rearward motion to the track balls, whereas both of
35 the two left side track balls and both of the two right side track balls are engaged by a respective pair of longitudinally extending drive shafts which, when rotated by respective motors impart left or right transverse motion to the track balls, with each drive shaft pair at
at least one end thereof being driven by a separately activatable motor, so that each shoe can be moved on the

- 15 -

ground in any direction.

8. A device as claimed in any one of claims 3 or 5 to 7, wherein each shoe incorporates an additional positional sensor so that the controller can sense any deviation that each foot has from a forward facing orientation when standing and a forwardly directed walking orientation when walking, and so that the motive means is activated accordingly by the controller to return the user to the datum.

9. A device as claimed in claim 4, wherein the motive means includes a plurality of track balls arranged within a floor, such that when standing thereon, the user's feet or shoes engage a certain number of track balls, and wherein when the user is walking on the floor a predetermined number of track balls are driven by a motor means that is activated responsive to the signal from the controller so that the user's feet (or shoes) are moved to return the user to the datum.

10. A device as claimed in claim 9, wherein the motor means is a plurality of motors, each arranged for driving one or more drive shafts that are either longitudinally or transversely arranged within the floor, and so that each drive shaft contacts a plurality of track balls in a given row through the floor.

11. A device as claimed in any one of the preceding claims, wherein the datum is:

(a) an area in which the user is to be maintained; or

(b) an imaginary vertical axis that is determined by the controller;

so that the controller operates the motive means until the positional sensor is positioned within the area or is at a predetermined location with respect to the axis.

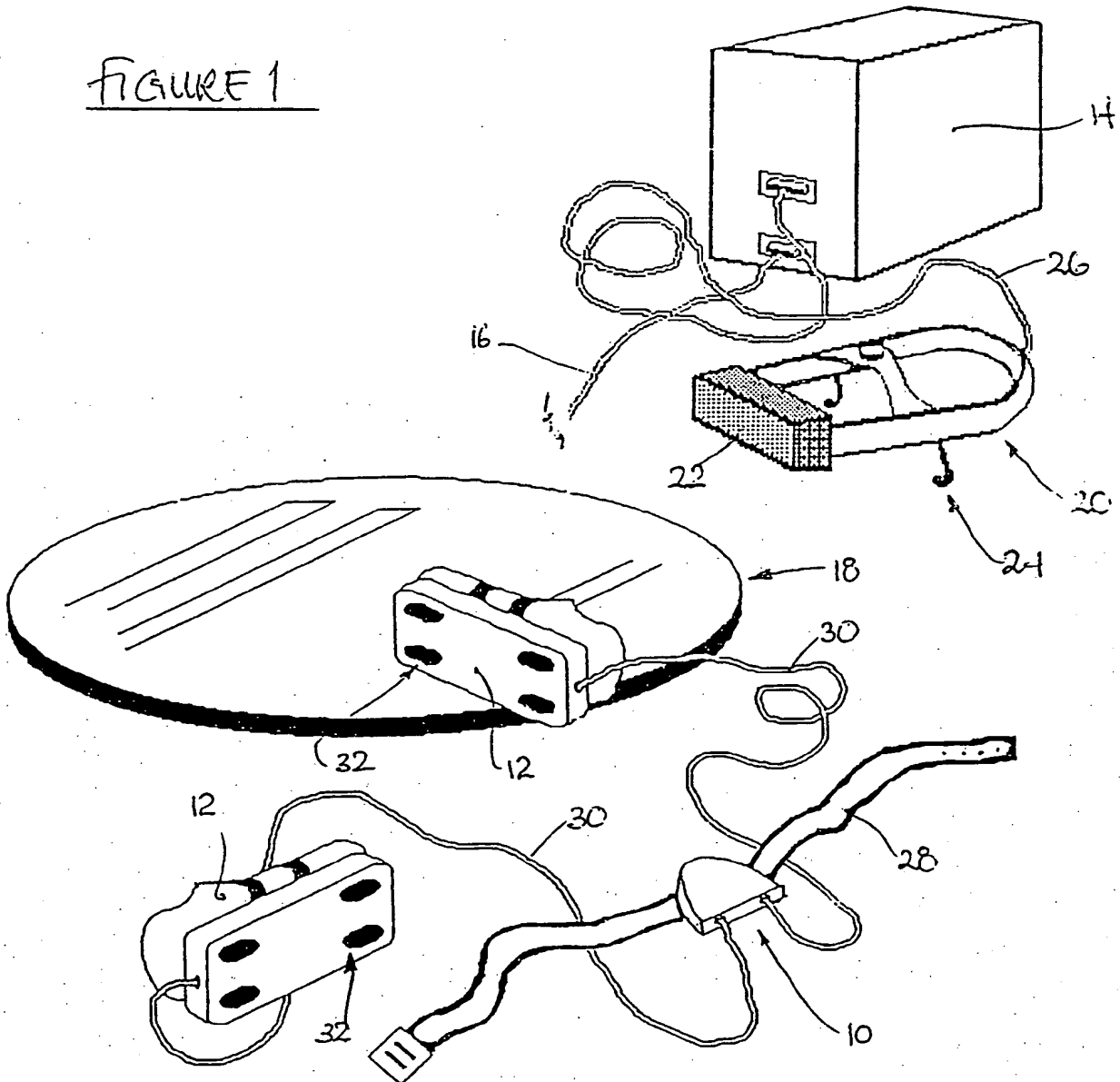
- 16 -

12. A device as claimed in any one of the preceding claims, wherein the positional sensor is adapted for being positioned at or close to the user's centre of gravity for early sensing of user walking movement, and
5 optionally at the user's navel or forehead.

13. A device as claimed in any one of the preceding claims when used in conjunction with virtual reality simulation apparatus.

14. A device as claimed in claim 13, wherein each
10 movement of the user from the datum is simulated by a processor and is reproduced in a virtual realm perceivable by the user.

15. A device as claimed in claim 14, wherein the device is used to return the user to the datum when walking,
15 whereas that walking is simulated in the virtual realm.

FIGURE 1

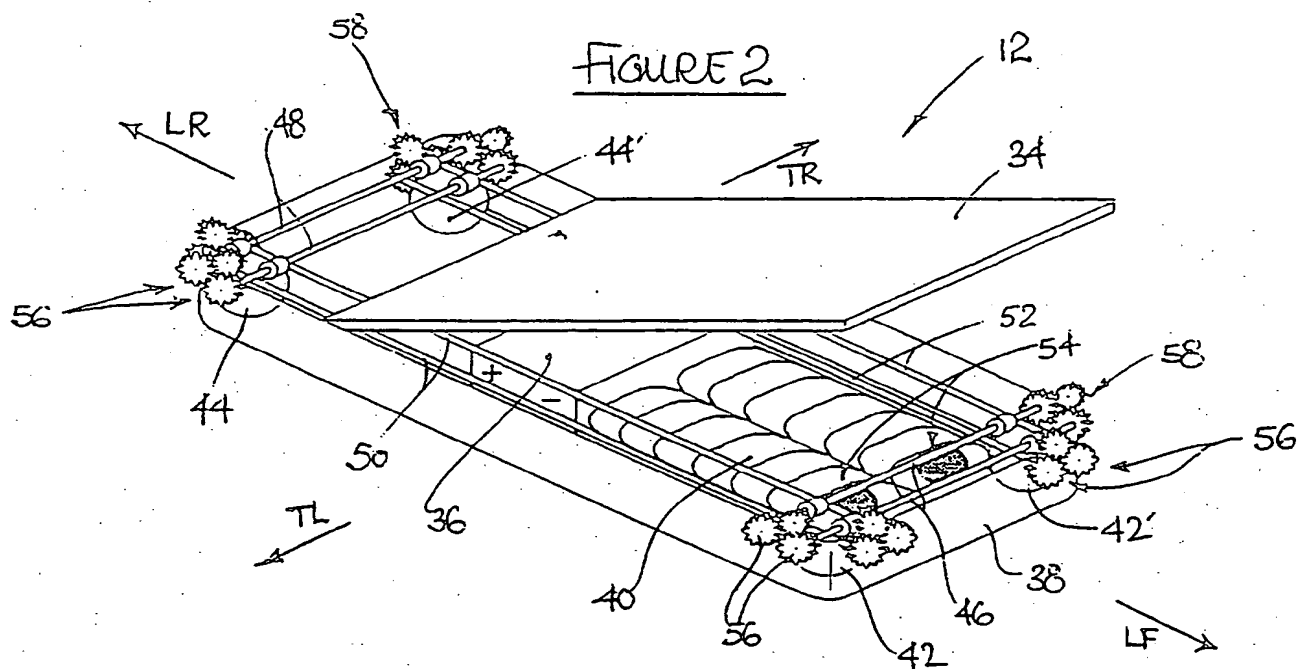


FIGURE 3

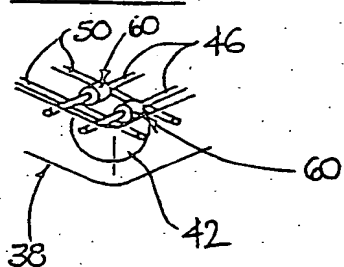
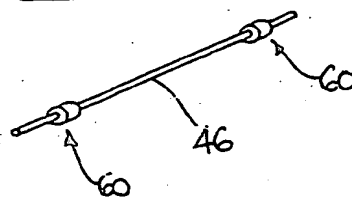
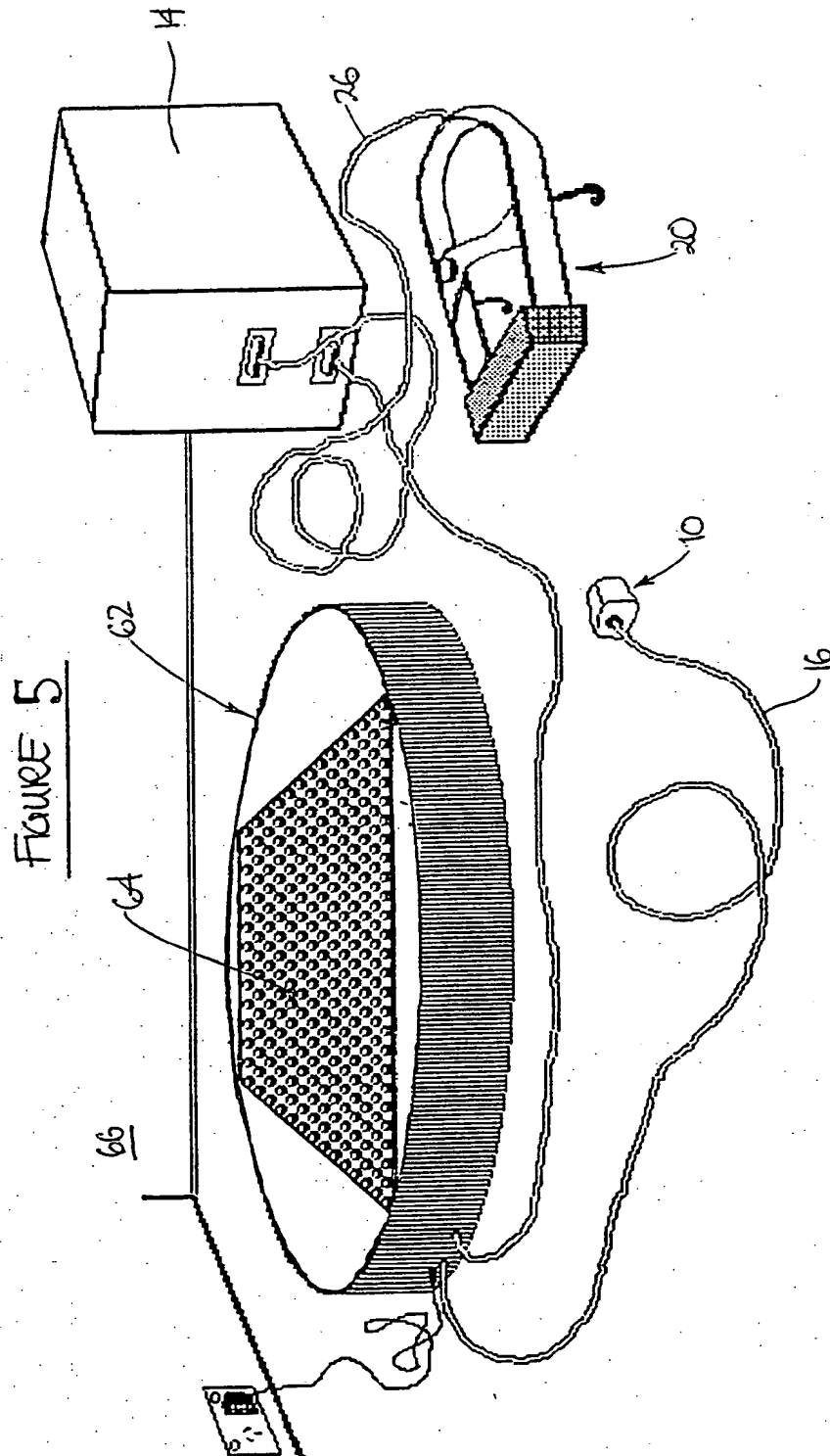


FIGURE 4





INTERNATIONAL SEARCH REPORT

International Application No.
PCT/AU 96/00298

A. CLASSIFICATION OF SUBJECT MATTER

Int Cl⁶: G09B 9/00

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

Int. Cl. G09B 9/00 A63C 17/12 B65G 13/04 A63B 22/02

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched
AU : IPC as above

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	FR 2677257 A (REMLINGER) 11 December 1992	
A	US 5048632 A (BATTEL) 17 September 1991	
A	EP 441104 A (BETA BELLAROSA) SpA) 14 August 1991	

☒ Further documents are listed in the continuation of Box C

☒ See patent family annex

* Special categories of cited documents:

"A" document defining the general state of the art which is not considered to be of particular relevance
 "E" earlier document but published on or after the international filing date
 "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)
 "O" document referring to an oral disclosure, use, exhibition or other means
 "P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention
 "X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone
 "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art
 "&" document member of the same patent family

Date of the actual completion of the international search
5 July 1996

Date of mailing of the international search report
18 JUL 1996

Name and mailing address of the ISA/AU
AUSTRALIAN INDUSTRIAL PROPERTY ORGANISATION
PO BOX 200
WODEN ACT 2606
AUSTRALIA Facsimile No.: (06) 285 3929

Authorized officer

J.W. THOMSON

Telephone No.: (06) 283 2214

PCT/INTERNATIONAL SEARCH REPORT

International Application No.

PCT/AU 96/00298

C (Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	DE 3933999 A (ERICH JAEGER GmbH & Co KG) 18 April 1991	
A	US 4991126 A (REITER) 5 February 1991	
A	EP 394146 A (GIP EXERCISE et al) 24 October 1990	
A	US 4917375 A (LIN) 17 April 1990	
A	US 4715460 A (SMITH) 29 December 1987	
A	US 4508187 A (WENZEL) 2 April 1985	

INTERNATIONAL SEARCH REPORT

International Application No.
PCT/AU 96/00298

This Annex lists the known "A" publication level patent family members relating to the patent documents cited in the above-mentioned international search report. The Australian Patent Office is in no way liable for these particulars which are merely given for the purpose of information.

Patent Document Cited in Search Report				Patent Family Member			
US	5048632	EP	367645	FR	2638977		
US	4991126	AT	386683	AU	73904/87	AU	594780
		DE	3777825	EP	304419	JP	1502609
		WO	8707012				
US	4917375	AT	90583	CN	2066340	DE	68907212
		EP	413871				
US	4715460	AU	52022/86	EP	201592	WO	8603132
EP	441104	IT	9040019				
EP	394146	AT	93737	CA	2014395	DE	69002995
		EP	394146	ES	2044506	FR	2645753
		JP	3063074				
END OF ANNEX							